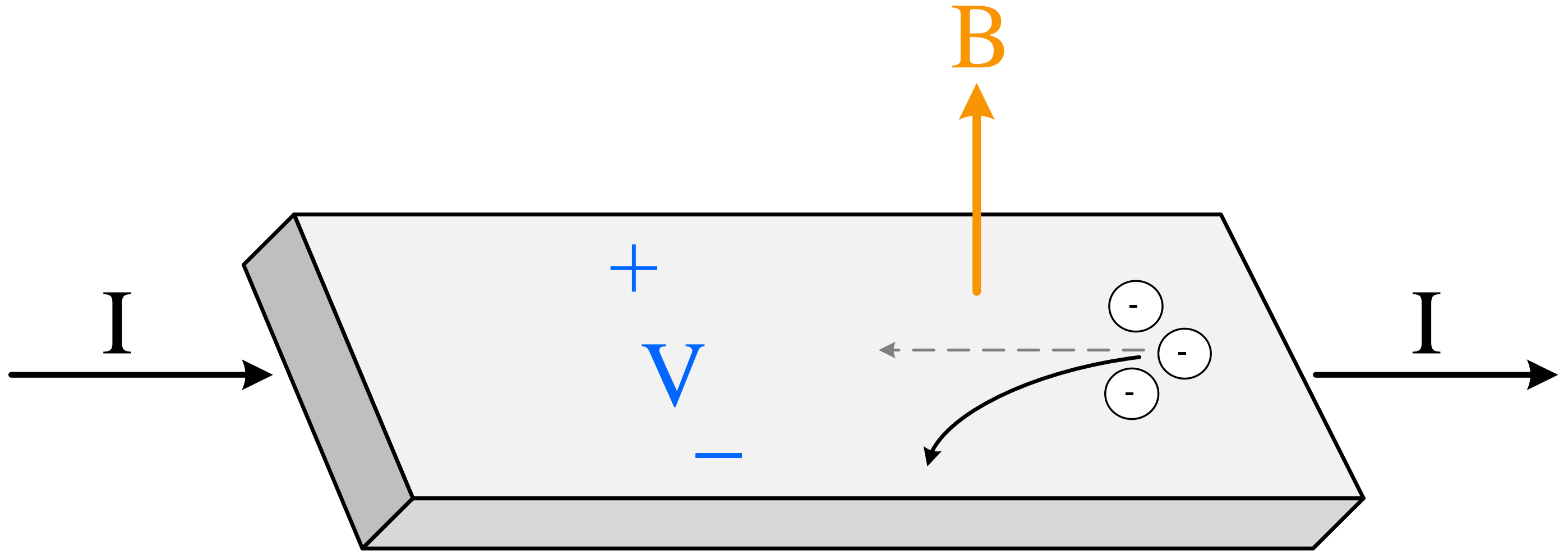


# Introduction to Hall Effect Sensing

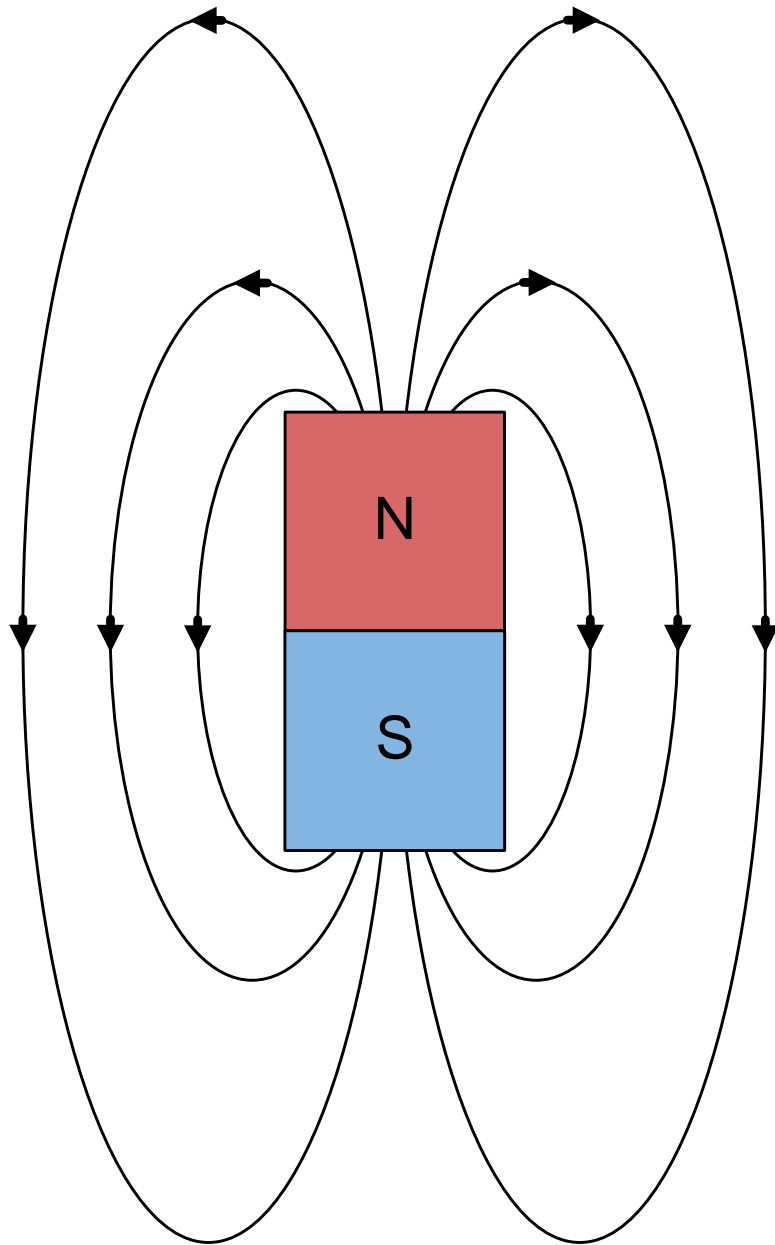
TI Precision Labs – Magnetic Position Sensing

Presented and prepared by Gloria Kim

# What is Hall effect?



# Permanent magnet

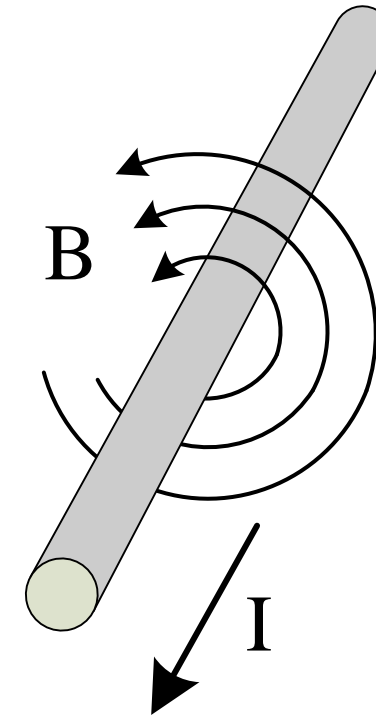
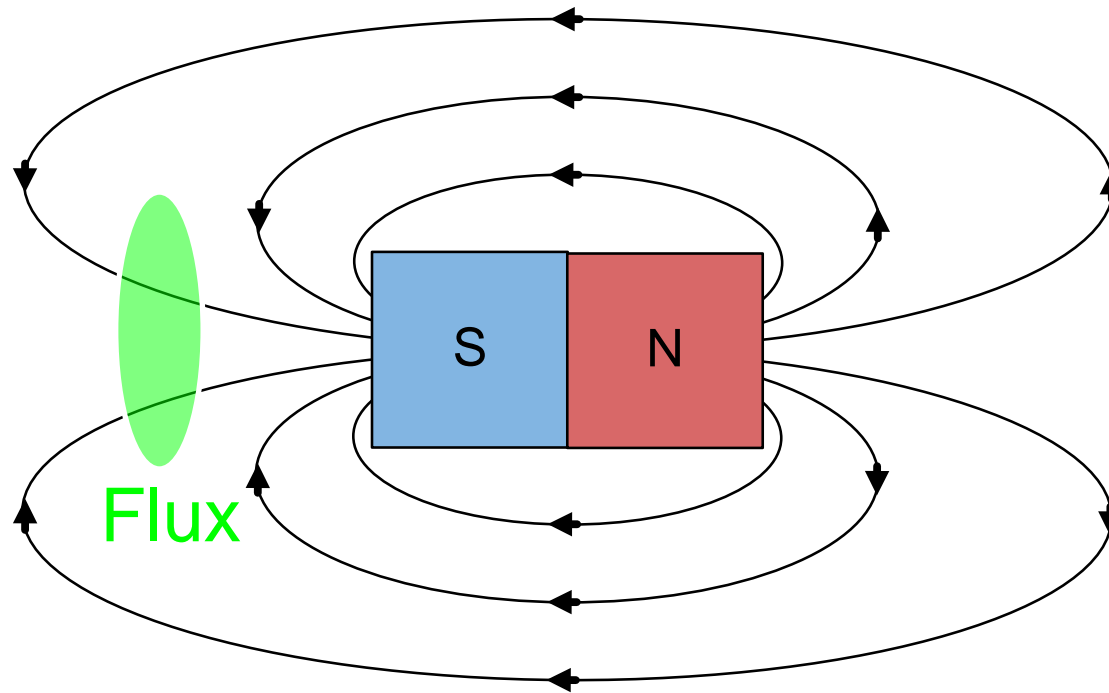


- Neodymium-Iron-Boron (NdFeB)
  - Highest  $B_r$
  - -11% per +100°C
- Ferrite (iron-oxide ceramic)
  - Low-cost, but 30%  $B_r$  of NdFeB
  - -20% per +100°C
- Aluminum-Nickel-Cobalt (AlNiCo)
  - Temperature consistency
  - -2% per +100°C
- Samarium-Cobalt (SmCo)
  - Best for high temperatures
  - -4% per +100°C



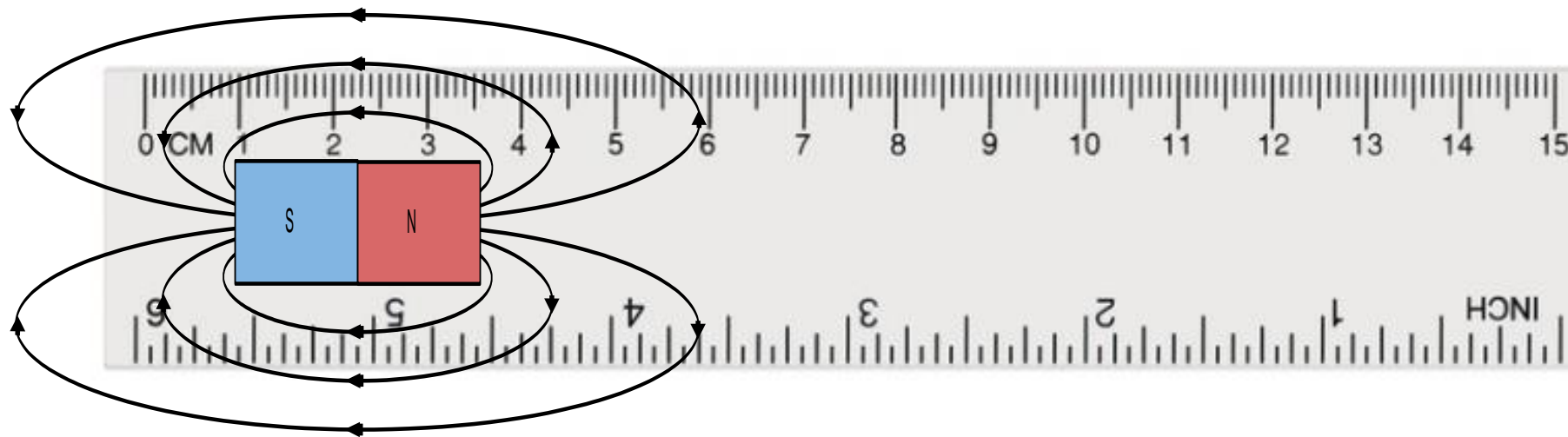
# Magnets and flux density

- Two main sources: magnets and current
- “Flux”: the sum of magnetic field lines passing through a specified area.
- “Flux density”: magnetic force
  - Flux per  $\text{mm}^2$
  - Units: gauss (G) or tesla (T)
  - $10 \text{ G} = 1 \text{ mT}$
  - Earth’s field  $\approx 0.05 \text{ mT}$



# Determining a magnet's flux density vs. distance

1. Magnet datasheet
2. Simulation (FEMM, COMSOL, ANSYS Maxwell)
3. Measurement (gaussmeter/teslameter, linear Hall)
4. TI magnetic field calculator



Magnetic Field Calculator

Magnet Material:

Remanence (Br):  Gauss

Magnet Shape:  Rectangle  Cylinder

Width:

Length:

Thickness:

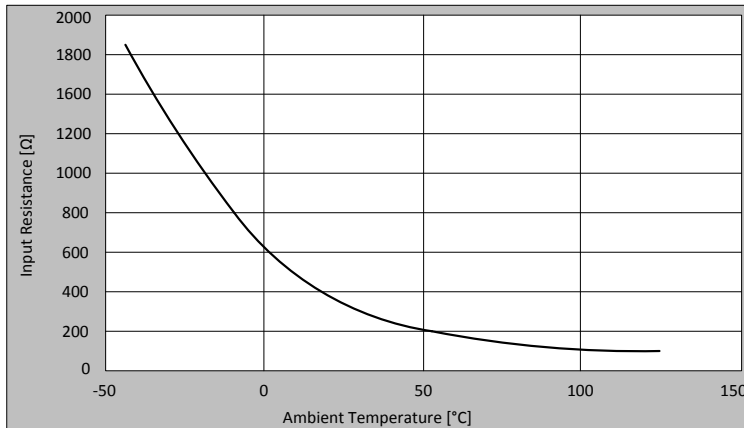
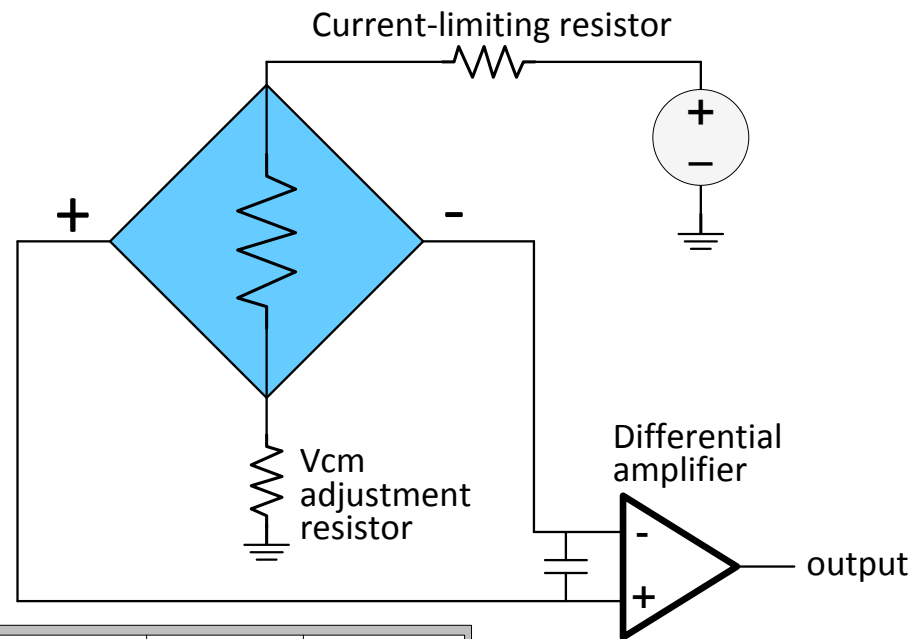
A 3D diagram of a rectangular magnet with a blue South (S) pole and a red North (N) pole. The dimensions are labeled: Width, Length, and Thickness. Magnetic field lines are shown looping around the magnet. A green arrow labeled 'B' indicates the direction of the magnetic flux density at a distance from the magnet.

Distance:

Magnetic flux density  $B = 26.05$  mT

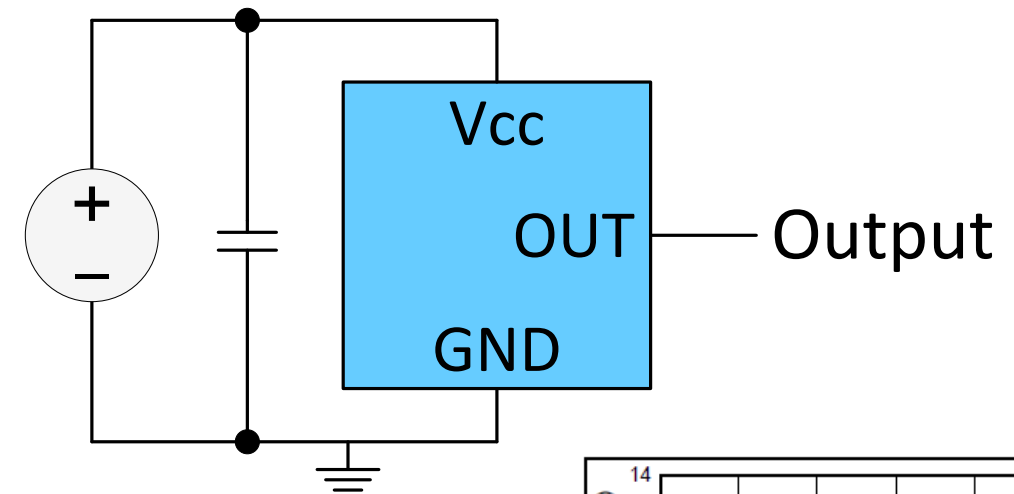
# Industry devices: Hall elements and ICs

## Element



- Passive component
- Requires signal conditioning
- Less robust
- Element resistance varies ten times across temperature

## Integrated Circuit



- Protection, robustness
- Fully integrated analog design
- Temperature compensation
- Many different device classes

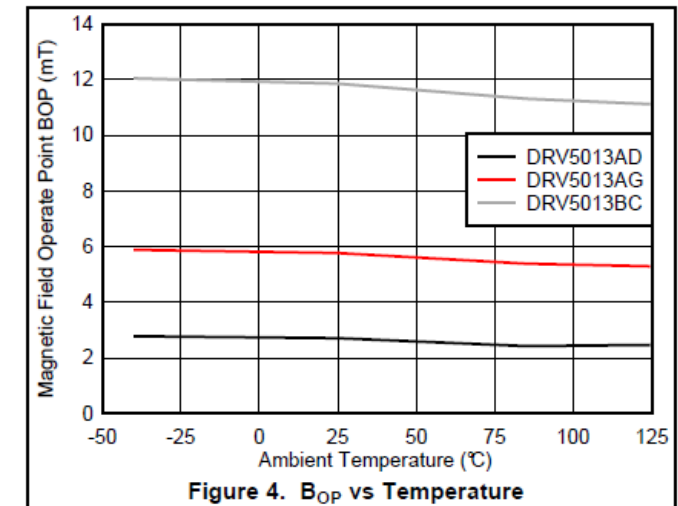
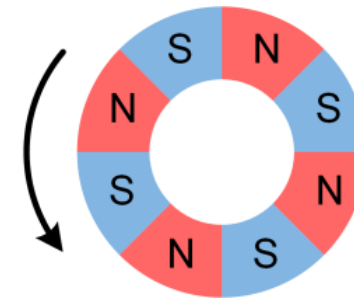
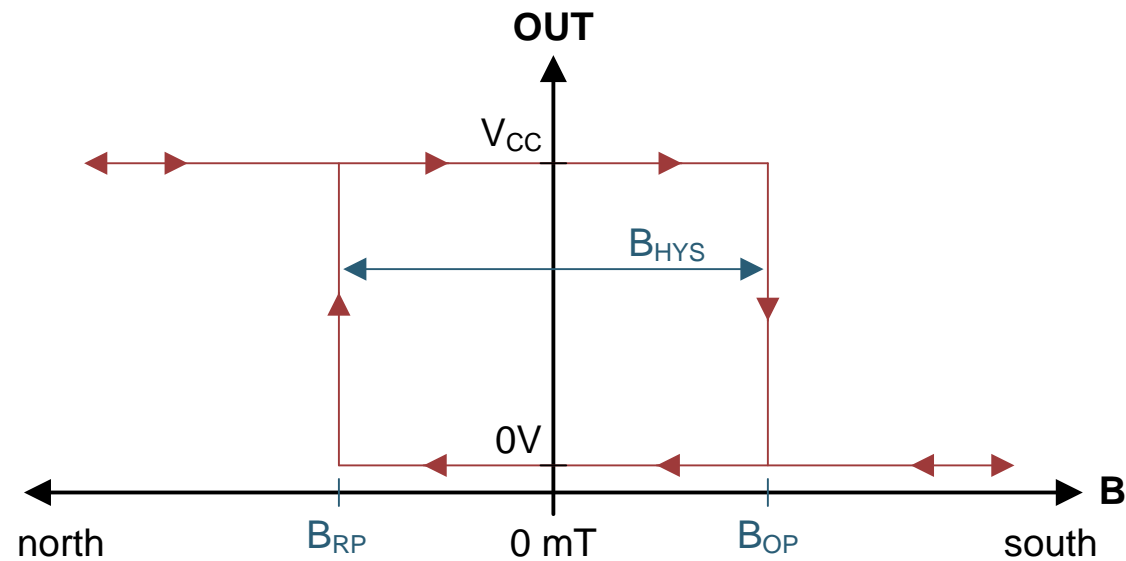


Figure 4. B<sub>OP</sub> vs Temperature

# Hall effect latches

## Hall effect latch

Indicates the most recently measured magnetic flux density. These are used in rotary applications such as BLDC motor sensors and incremental encoding.



- Motors
- Incremental encoders

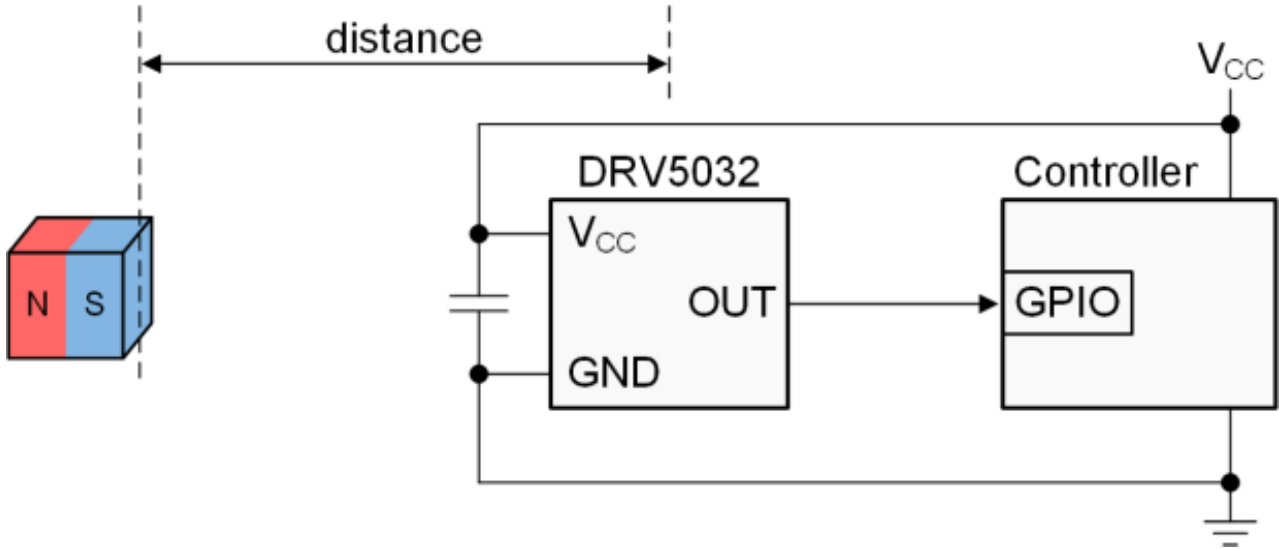
Incremental Rotary Encoder Design Considerations  
<http://www.ti.com/lit/pdf/sboa200>

# Hall effect switch

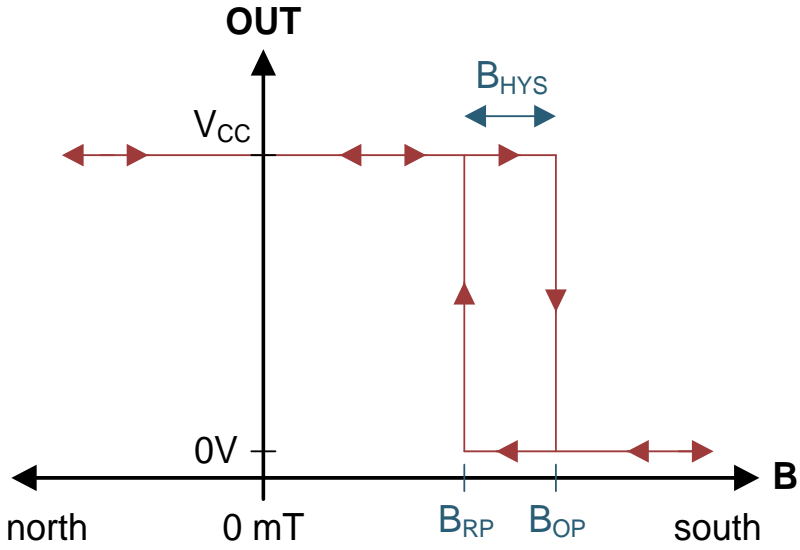
## Hall effect switch

Indicates the presence or absence of magnetic flux density compared to a defined threshold.

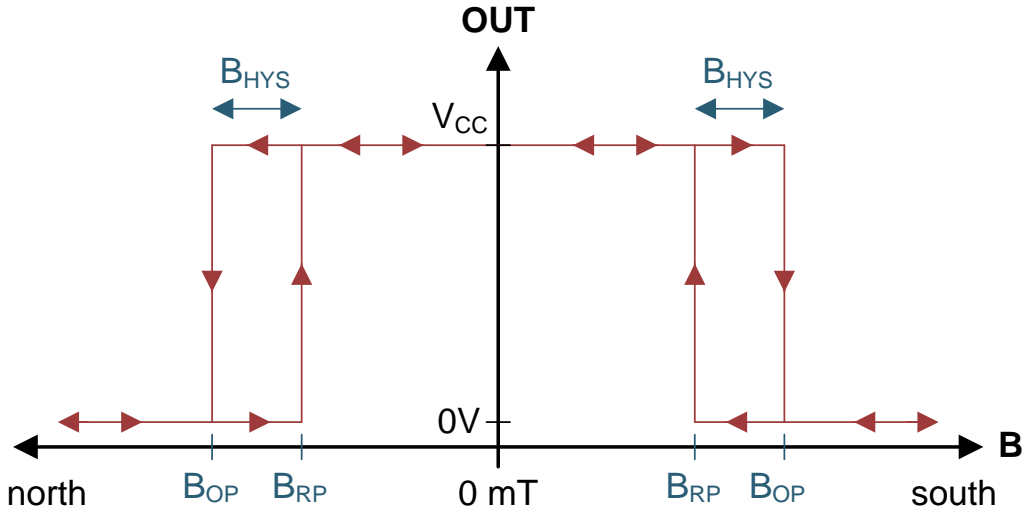
- Unipolar switch – responds only to south magnetic poles
- Omnipolar switch – responds to both south and north magnetic poles



Unipolar



Omnipolar



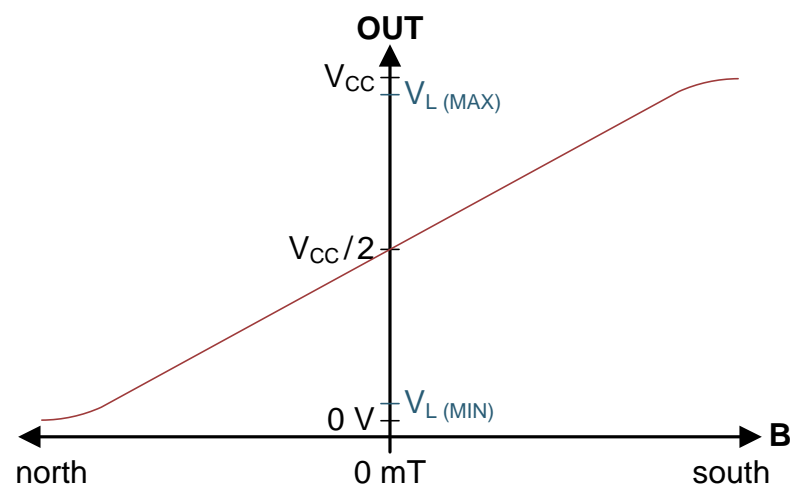


# Single-axis linear Hall effect sensor

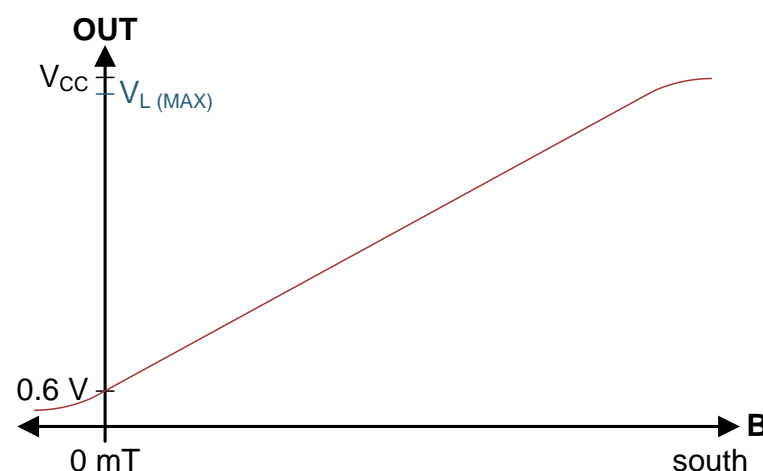
## Linear Hall effect sensors

Outputs a signal that is proportional to magnetic flux density in order to measure precise movement.

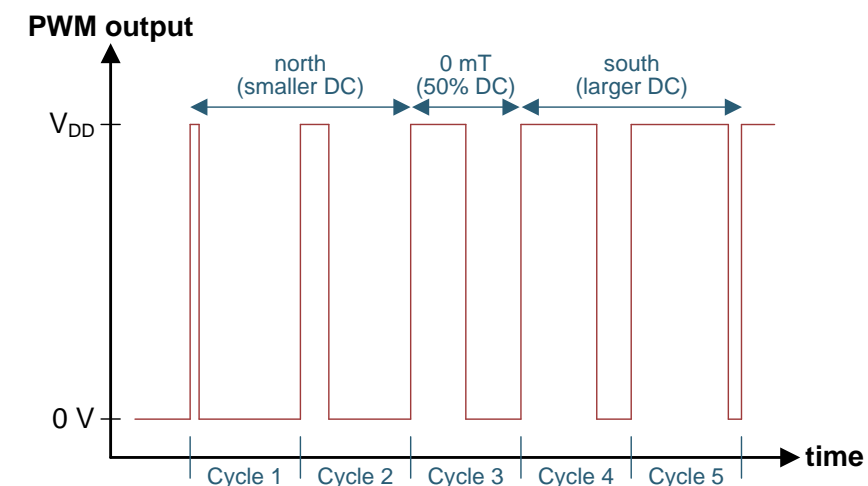
### Bipolar measurement with analog output



### Unipolar measurement with analog output

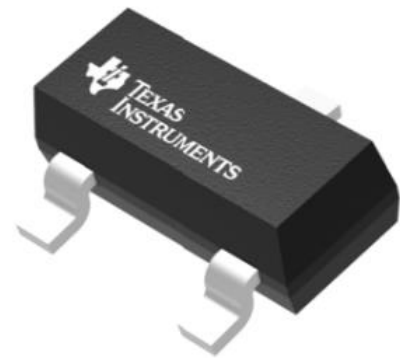
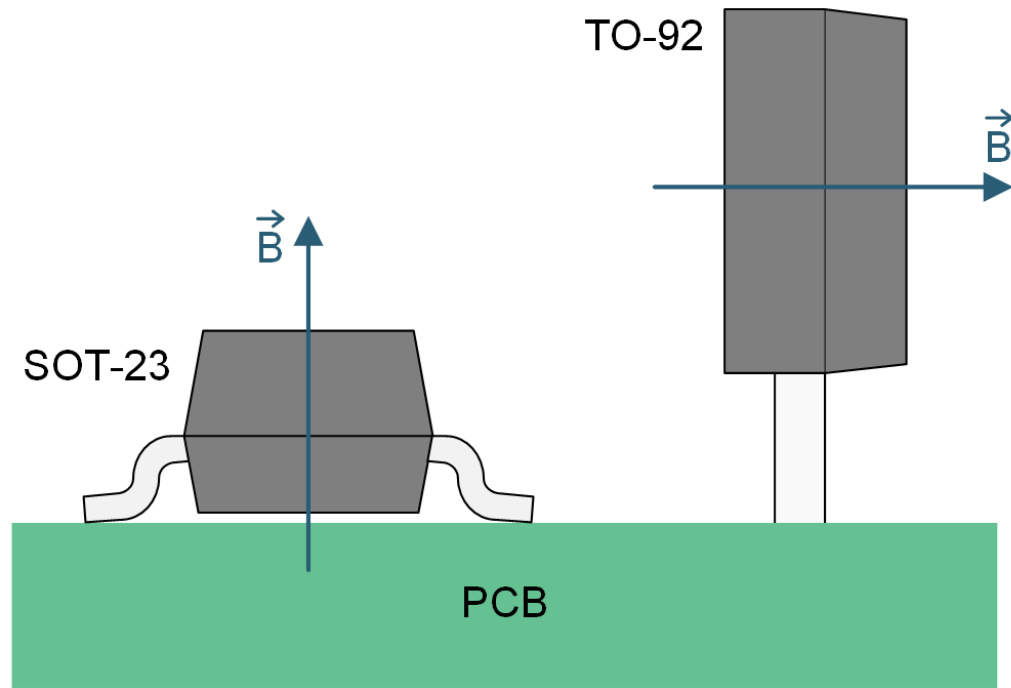


### Bipolar measurement with PWM output

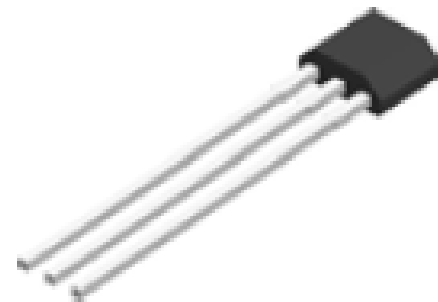


# Common package types

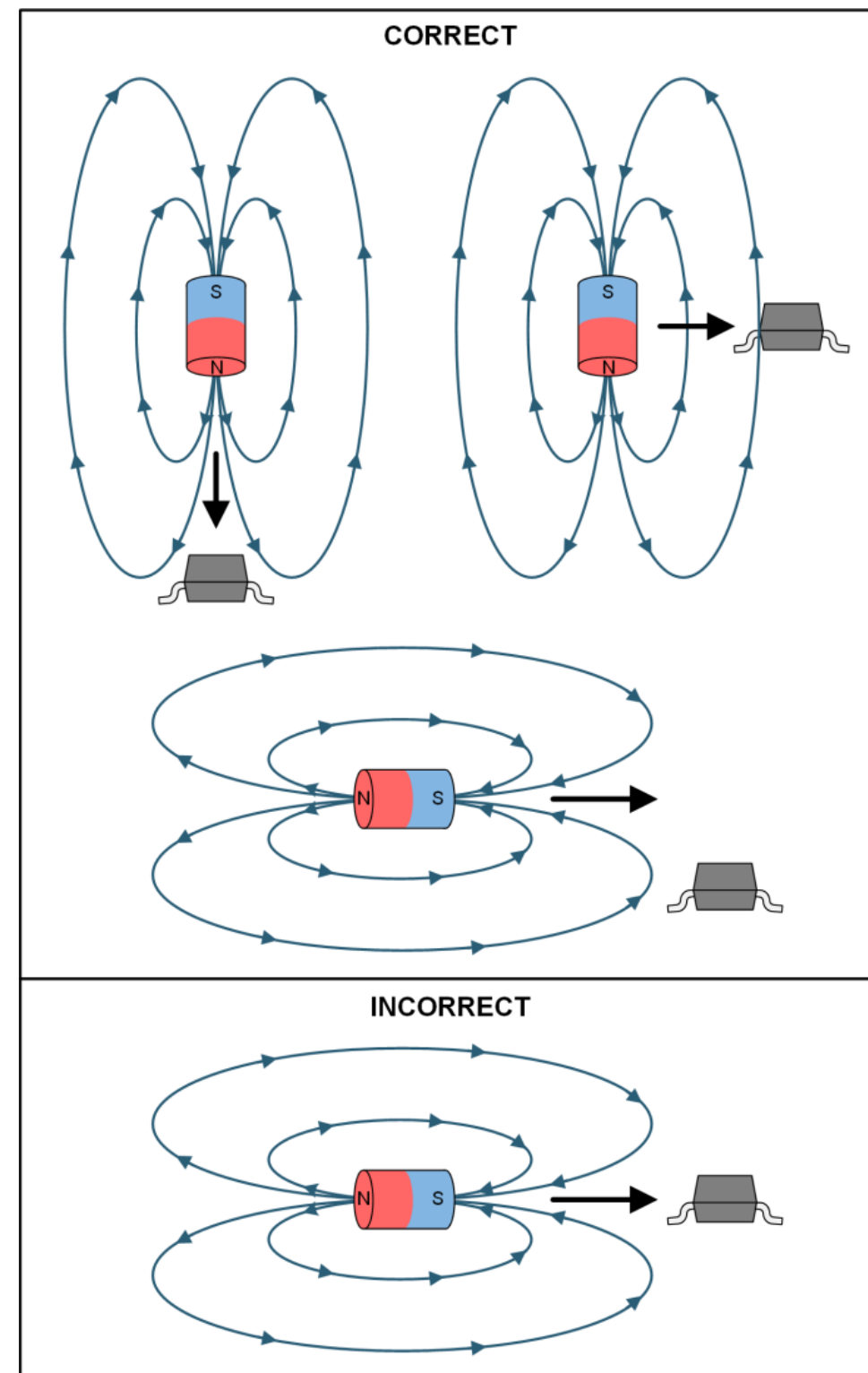
2 packages, 2 sensing directions



**SOT-23**



**TO-92 or "SIP"**



To find more magnetic position sensing technical resources and search products, visit [ti.com/halleffect](https://ti.com/halleffect)